

## ANALYSIS AND SYNTHESIS FOR INTERVAL TYPE 2 FUZZY MODEL BASED SYSTEMS

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Tracking control design of interval type-2 polynomial

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1. Introduction. Analysis of nonlinear control systems is generally challenging due to their complexity in nature. An effective way to represent the dynamics of the complex nonlinear control system is the Takagi-Sugeno (T-S) fuzzy-model-based (FMB) approach Takagi and Sugeno (1985), Sugeno and Kang (1988), in which a family of local linear