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KHALID BIN ISA Department of Computer Engineering,
Faculty of Electric and Electronic Engineering, University
College of
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...
Autonomous control systems are designed to perform well
under significant uncertainties in the system and
environment for extended periods of time, and they must
be able to
[Creating Control Systems For Autonomous Vehicles](#)
Any lessons learned will enable design teams to give their
autonomous control systems more responsibility for when
they can take and retain control of the car. These
improvements should then be pushed out to existing
vehicles in regular software updates.
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increasing software complexity and the related hardware
requirements as well as with the development of
autonomous operating machines and functions, new
hardware and software architectures such as autonomous
control systems are becoming increasingly important in the
field of mobile working machines.
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[Khalid Isa ...](#)
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drive and the steering system lead to very complex. Also,
for the vehicle to be in moment equilibrium models, with
the help of which an attempt can be about the centre of
gravity, the sum of the made to simulate the vehicle's
handling over a moments from the front and rear lateral
forces period. However, a few of the basic considerations
must be
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decision-making Article (PDF Available) in Proceedings of the Institution of Mechanical Engineers Part I Journal of Systems and Control Engineering

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Our fundamental and applied research on autonomous systems and controls aims to enable greater autonomy for explorations of land, sea, sky and space. Our current applications of interest include robotic transportation networks, mapping and navigation in extreme environments, planning and control for agile robotic systems, air traffic management.

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[Autonomous cruise control system - Wikipedia](#)

Autonomous cruise control (ACC; also called adaptive cruise control, radar cruise control, traffic-aware cruise control or dynamic radar cruise control) is an optional cruise control system for road vehicles that automatically adjusts the vehicle speed to maintain a safe distance from vehicles ahead.

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The transportation methodologies followed nowadays have

evolved a lot with the implementation of embedded features in it. With the trends in today's autonomous vehicles driven by batteries with electric drives (EVs), the present paper deals with one of the key features of autonomous vehicle, Fuzzy based Lidar sensor model. [Autonomous Control System | ASV Global | World Leading ...](#)

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