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[H[∞] Optimal Control and Filtering](#) 5.1 Basic H[∞] Controllers of Linear System 5.2 Singularly Perturbed Optimal H[∞] Control Prob 5.3 Solution of the Singularly Perturbed H[∞] Algebraic Riccati 5.3.1 Case Study: H[∞] Optimal Control of an F-8 Aircraft 5.4 Hoc Filterin 5.5 HCQ Filter fo 5.5.1 Decomposition of the H[∞] Filter Algebraic Riccati E

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Since minimizing the H-induced norm as defined above, over the set of admissible controllers is a difficult problem (i.e., the optimal H-control problem is difficult to solve exactly [92, 101]), whereas minimizing the induced H₂-norm and obtaining optimal H₂-controllers is an easy problem, the objective of the mixed H₂/H design philosophy is to minimize PL₂ (equivalently P₂) while rendering

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[1.4 OPTIMUM DESIGN VERSUS OPTIMAL](#)

[CONTROL](#) What Is Optimal Control? Optimum design and optimal control of systems are separate activities.

There are numerous applications in which methods of optimum design are useful in designing systems. There are many other applications where optimal control concepts are needed. In addition, there are some applications in which both optimum design and optimal

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